

# NUMERICAL ANALYSIS QUALIFIER

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**Problem 1.** Let  $\Omega$  be a polygonal domain in  $\mathbf{R}^2$  and assume that  $0 \in \Omega$ . Let  $u \in H^1(\Omega)$  be the solution of

$$(1.1) \quad a(u, \varphi) = l(\varphi), \quad \text{for all } \varphi \in H^1(\Omega),$$

where the bilinear form  $a(\cdot, \cdot)$  and, for a given function  $f \in L^2(\Omega)$ , the right hand side  $l(\cdot)$  are defined as follows,

$$a(v, \varphi) := \int_{\Omega} (\nabla v \cdot \nabla \varphi + \|x\|^2 v \varphi) dx, \quad l(\varphi) := \int_{\Omega} f \varphi dx \quad \text{for all } v, \varphi \in H^1(\Omega).$$

Let  $\mathcal{T}_h$ ,  $0 < h < 1$ , be a family of shape regular triangulations of  $\Omega$ . The elements of these partitions will be denoted by  $T_h$ . Set

$$V_h := \{v_h \in H^1(\Omega) : v_h|_{T_h} \in \mathcal{P}^1, \quad T_h \in \mathcal{T}_h\},$$

where  $\mathcal{P}^1$  denotes the space of polynomials on  $\mathbf{R}^2$  of degree at most 1.

(a) Show that the bilinear form  $a(\cdot, \cdot)$  is coercive in  $H^1(\Omega)$ .

*Hint:* Decompose  $\Omega$  into  $\Omega_i := \Omega \cap B_\varepsilon(0)$  and  $\Omega_o := \Omega \setminus \Omega_i$ , where  $B_\varepsilon(0)$  is a disc with radius  $\varepsilon$  around 0 such that  $B_\varepsilon(0) \subset \Omega$ . **You can use without proof that**

$$\|v\|_{L^2(\Omega)}^2 \leq C \{ \|v\|_{L^2(\Omega_o)}^2 + \|\nabla v\|_{L^2(\Omega^2)}^2 \}$$

for all  $v \in H^1(\Omega)$ , for a suitable constant  $C \geq 1$  depending on  $\varepsilon$  but independent of  $v$ .

(b) Given that  $a(\cdot, \cdot)$  and  $l(\cdot)$  are continuous, there exists a unique weak solution  $u \in H^1(\Omega)$  of (1.1). Derive the strong form of problem (1.1) assuming that the solution  $u$  is smooth.

Now, consider the following finite element ansatz: find  $u_h \in V_h$  such that

$$(1.2) \quad a(u_h, \varphi_h) = l(\varphi_h), \quad \forall \varphi_h \in V_h.$$

(c) State and prove Cea's Lemma for the error of the FE solution in the  $H^1$ -norm.

(d) Assuming that the solution  $u$  is in  $H^2(\Omega)$ , derive an estimate for the error  $\|u - u_h\|_{H^1(\Omega)}$ . Your final estimate should reflect the correct order of convergence with respect to the mesh parameter  $h$ . You may use without proof suitable approximation results for the finite element space  $V_h$ .

**Problem 2.** Consider the unit interval  $\Omega = (0, 1)$  and the following 1D parabolic problem:

$$\partial_t u(x, t) - \partial_{xx} u(x, t) = f(t, x), \quad \text{for } x \in \Omega, t \in (0, T],$$

$$u(t, 0) = u(t, 1) = 0 \quad \text{for } t \in (0, T],$$

$$u(0, x) = u_0(x), \quad \text{for } x \in \Omega.$$

Here,  $f(t, x)$  and  $u_0(x)$  are given, smooth functions.

(a) Derive the variational (in space) formulation of the above problem. What is a suitable function space  $V$ ?

(b) Discretize the variational formulation in time only (Rothe's method) with the backward Euler scheme.

- (c) Let now  $\{\psi_j\}_{j=1}^{\infty} \subset H^2(\Omega) \cap H_0^1(\Omega)$  be an orthonormal (in  $L_2(\Omega)$ ) eigenbasis of  $-\partial_{xx}$  with homogeneous Dirichlet boundary conditions with corresponding eigenvalues  $0 < \lambda_1 \leq \lambda_2 \leq \lambda_3 \dots$ . That is,

$$-\partial_{xx}\psi_j(x) = \lambda_j\psi_j(x), \quad x \in (0, 1), \quad \psi_j(0) = \psi_j(1) = 0, \quad \|\psi_j\|_{L_2(0,1)} = 1, \quad \int_0^1 \psi_i\psi_j = \delta_{ij}.$$

Now, write the semi discrete solution defined in part (b) as follows:

$$u_k^n = \sum_{j=1}^{\infty} c_j^n \psi_j(x),$$

where  $k$  is the time-step size,  $t_n$  denotes the time point  $t_n = kn$ . Derive the equation following relation for  $c_j^n$ :

$$\frac{c_j^{n+1} - c_j^n}{k} + \lambda_j c_j^{n+1} = F_j^{n+1}, \quad j = 0, 1, 2, \dots$$

where  $F_j^{n+1} := \int_0^1 f(t_{n+1}, x)\psi_j(x)dx$ .

- (d) Prove the coefficientwise stability result

$$|c_j^{n+1}| \leq q_j^{n+1} |c_j^0| + k \sum_{m=1}^{n+1} q_j^{n+2-m} |F_j^m|, \quad \text{where } q_j := \frac{1}{1 + k\lambda_j}.$$

Using that  $\|u_k^n\|_{L_2(0,1)} = (\sum_{j=1}^{\infty} (c_j^n)^2)^{1/2}$ , conclude that if  $f = 0$ , then

$$\|u_k^n\|_{L_2(0,1)} \leq \|u_0\|_{L_2(0,1)}.$$

**Problem 3.** Let  $K$  be a nondegenerate triangle in  $\mathbf{R}^2$ . Let  $a_1, a_2, a_3$  be the three vertices of  $K$ . Let  $a_{ij} = a_{ji}$  denote the midpoint of the segment  $(a_i, a_j)$ ,  $i, j \in \{1, 2, 3\}$  and  $i \neq j$ . Let  $\mathcal{P}^2$  be the set of the polynomial functions over  $K$  of total degree at most 2. Let  $\Sigma = \{\sigma_1, \sigma_2, \sigma_3, \sigma_{12}, \sigma_{23}, \sigma_{31}\}$  be the functionals (or degrees of freedom) on  $\mathcal{P}^2$  defined as

$$\sigma_i(p) := p(a_i), \quad i \in \{1, 2, 3\} \quad \sigma_{ij}(p) := p(a_i) + p(a_j) - 2p(a_{ij}), \quad i, j = 1, 2, 3, \quad i \neq j.$$

- (a) Show that  $\Sigma$  is a unisolvent set for  $\mathcal{P}^2$  (this means that any  $p \in \mathcal{P}^2$  is uniquely determined by the values of the above degrees of freedom applied to  $p$ ).
- (b) Compute the “nodal” basis  $\{\psi_j\}_{j=1}^6$  of  $\mathcal{P}^2$  which corresponds to  $\{\sigma_1, \dots, \sigma_{31}\}$ .

*Hint for part (a) and (b):* Use barycentric coordinates.

- (c) Given  $u \in C^0(K)$ , define an interpolation operator  $I_h$  by

$$(I_h u)(x) = \sum_{j=1}^3 \sigma_j(u)\psi_j(x) + \sigma_{12}(u)\psi_4(x) + \sigma_{23}(u)\psi_5(x) + \sigma_{31}(u)\psi_6(x).$$

Show the following:

- (i)  $I_h u = u$  if  $u \in \mathcal{P}^2$ .
- (ii) There is a constant  $C$  independent of  $u$  and  $K$  such that

$$\|I_h u\|_{L_{\infty}(K)} \leq C \|u\|_{L_{\infty}(K)}.$$

- (iii) Finally deduce that

$$\|u - I_h u\|_{L_{\infty}(K)} \leq C \inf_{\chi \in \mathcal{P}^2} \|u - \chi\|_{L_{\infty}(K)}.$$